

Convex topological Space and some Continuous functions

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ABSTRACT

Some continuous functions has been introduced using both the topology τ and convexity \mathcal{C} on the same underlying set X where (X, τ, \mathcal{C}) is termed as convex topological space and inter relation with examples among them are also investigated.

Keywords: Convex topological space , $\tau - \mathcal{C}$ semi compatible , $\delta - \mathcal{C}$ continuous function , $\theta - \mathcal{C}$ continuous function , almost \mathcal{C} continuous function .

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1. Introduction : The development of “abstract convexity” has emanated from different sources in different ways ; the first type of development basically banked on generalization of particular problems such as separation of convex sets [3] , extremality [4] , [2] or continuous selection [12] . The second type of development lay before the reader such axiomatizations , which in every case of design , express particular point of view of convexity . With the view point of generalized topology which enters into convexity via the closure or hull operator , Schmidt [1953] and Hammer [1955] , [1963] , [1963b] introduced some axioms to explain abstract convexity . The arising of convexity from algebraic operations and the related property of domain finiteness receive attentions in Birchoff and Frink [1948], Schmidt [1953] , Hammer [1963] .

In [15] the author has discussed “ Topology and Convexity on the same set” and introduced the compatibility of the topology with a convexity on the same underlying set . At the very early stage of this paper we have set aside this concept of compatibility and started just with a triplet (X, τ, \mathcal{C}) and call it convex topological space only to bring back “compatibility” in another way subsequently . With this compatibility , Van De Val has called the triplet (X, τ, \mathcal{C}) a topological convex structure .

In this paper , Art. 2 deals with some early definitions , results and in Art. 3 we have discussed mainly inter relation among different types of continuous functions .

2. Prerequisites :

Definition 2.1 : [15] Let X be a non empty set . A family \mathcal{C} of subsets of the set X is called a convexity on X if

1. $\phi, X \in \mathcal{C}$
2. \mathcal{C} is stable for intersection , i.e. if $\mathcal{D} \subseteq \mathcal{C}$ is non empty , then $\cap \mathcal{D} \in \mathcal{C}$
3. \mathcal{C} is stable for nested unions , i.e. if $\mathcal{D} \subseteq \mathcal{C}$ is non empty and totally ordered by set inclusion , then $\cup \mathcal{D} \in \mathcal{C}$.

The pair (X, \mathcal{C}) is called a convex structure . The members of \mathcal{C} are called convex sets and their complements are called concave sets .

Definition 2.2 : [15] Let \mathcal{C} be a convexity on set X . Let $A \subseteq X$. The convex hull of A is denoted by $co(A)$ and defined by $co(A) = \cap \{C : A \subseteq C \in \mathcal{C}\}$.

Note 2.3 : [15] Let (X, \mathcal{C}) be a convex structure and let Y be a subset of X . The family of sets $\mathcal{C}_Y = \{C \cap Y : C \in \mathcal{C}\}$ is a convexity on Y ; called the relative convexity of Y .

Note 2.4 : [15] The hull operator co_Y of a subspace (Y, \mathcal{C}_Y) satisfy the following :

$$\forall A \subseteq Y : co_Y(A) = co(A) \cap Y .$$

Definition 2.5 : [5] Let (X, τ) be a topological space and let \mathcal{C} be a convexity on X . Then the triplet (X, τ, \mathcal{C}) is called a convex topological space (CTS in short) .

Theorem 2.6 : [5] Let (X, τ, \mathcal{C}) be a convex topological space . Let A be a subset of X . Consider the set A_* , where A_* is defined as follows : $A_* = \{x \in X : co(U) \cap A \neq \emptyset, x \in U \in \tau\}$. Then the collection $\tau_* = \{A^c : A \subseteq X, A = A_*\}$ is a topology on X such that $\tau_* \subseteq \tau$.

Note 2.7 : [5] In a convex topological space (X, τ, \mathcal{C}) a subset A of X is said to be τ_* -closed if $A = A_*$.

Definition 2.8 : [5] Let (X, τ, \mathcal{C}) be a convex topological space . The space (X, τ, \mathcal{C}) is called $\tau - \mathcal{C}$ semi compatible if for every $A \in \tau$, A_* is a τ_* -closed set , i.e. if $A \in \tau$, then $(A_*)_* = A_*$.

Definition 2.9 : [5] Let (X, τ, \mathcal{C}) be a convex topological space and A be a subset of X . Then A is said to be an $R - \mathcal{C}$ open set if $\text{int}(A_*) = A$.

A subset B is called an $R - \mathcal{C}$ closed if B^c is an $R - \mathcal{C}$ open set.

Definition 2.10 : [7] Let (X, τ, \mathcal{C}) be a convex topological space. Let S be a subset of X and $x \in X$.

(a) x is called $\delta - \mathcal{C}$ cluster point of S if $S \cap \text{int}(U_*) \neq \emptyset$, for each open nbd. U of x .

(b) The family of all $\delta - \mathcal{C}$ cluster points of S is called the $\delta - \mathcal{C}$ closure of S and is denoted by $[S]_{\delta - \mathcal{C}}$.

(c) A subset P of X is called $\delta - \mathcal{C}$ closed if $[P]_{\delta - \mathcal{C}} = P$.

The complement of a $\delta - \mathcal{C}$ closed set is said to be a $\delta - \mathcal{C}$ open set.

Theorem 2.11 : [7] Let (X, τ, \mathcal{C}) be a convex topological space which is $\tau - \mathcal{C}$ semi compatible. Then we have the following properties :

- (1) If A is an open set, then $\text{int}(A_*)$ is an $R - \mathcal{C}$ open set.
- (2) If A and B are $R - \mathcal{C}$ open sets, then so is $A \cap B$.
- (3) If A is an $R - \mathcal{C}$ open set, then A is a regular open set.
- (4) $A \subseteq [A]_{\delta - \mathcal{C}}$.
- (5) If A is an $R - \mathcal{C}$ open set, then it is a $\delta - \mathcal{C}$ open set.
- (6) Every $\delta - \mathcal{C}$ open set is the union of family of $R - \mathcal{C}$ open sets.

Theorem 2.12 : [7] Let A and B be subsets of a convex topological space (X, τ, \mathcal{C}) which is $\tau - \mathcal{C}$ semi compatible. Then the following properties hold :

- (1) $A \subseteq B \Rightarrow [A]_{\delta - \mathcal{C}} \subseteq [B]_{\delta - \mathcal{C}}$.
- (2) $[A]_{\delta - \mathcal{C}} = \bigcap \{F \subseteq X : A \subseteq F \text{ and } F \text{ is } \delta - \mathcal{C} \text{ closed}\}$.
- (3) If A_α is $\delta - \mathcal{C}$ closed sets of X for each $\alpha \in \Lambda$, then so is $\bigcap_{\alpha \in \Lambda} (A_\alpha)$.
- (4) $[A]_{\delta - \mathcal{C}}$ is $\delta - \mathcal{C}$ closed set.

Remark 2.13 : [7] $[A]_{\delta - \mathcal{C}}$ is the smallest $\delta - \mathcal{C}$ closed set containing A .

Theorem 2.14 : [7] Let (X, τ, \mathcal{C}) be a convex topological space which is $\tau - \mathcal{C}$ semi compatible. Let $\tau_{\delta - \mathcal{C}} = \{A \subseteq X : A \text{ is a } \delta - \mathcal{C} \text{ open set in } X\}$. Then $\tau_{\delta - \mathcal{C}}$ is a topology on X such that $\tau_{\delta - \mathcal{C}} \subseteq \tau$.

Definition 2.15 : [8] Let (X, τ, \mathcal{C}_1) and $(Y, \sigma, \mathcal{C}_2)$ be two convex topological spaces. A function $f : (X, \tau, \mathcal{C}_1) \rightarrow (Y, \sigma, \mathcal{C}_2)$ is said to be $\delta - \mathcal{C}$ continuous if for each $x \in X$ and each open nbd. V of $f(x)$, there exists an open nbd. U of x such that $f(\text{int}(U_*)) \subseteq \text{int}(V_*)$.

Theorem 2.16 : [8] Let (X, τ, \mathcal{C}_1) and $(Y, \sigma, \mathcal{C}_2)$ be two convex topological spaces where (X, τ, \mathcal{C}_1) is $\tau - \mathcal{C}_1$ semi compatible and $(Y, \sigma, \mathcal{C}_2)$ is $\sigma - \mathcal{C}_2$ semi compatible. For a function $f : (X, \tau, \mathcal{C}_1) \rightarrow (Y, \sigma, \mathcal{C}_2)$ the following are equivalent :

1. f is $\delta - \mathcal{C}$ continuous.
2. For each $x \in X$ and each $R - \mathcal{C}$ open set V containing $f(x)$, there exists an $R - \mathcal{C}$ open set containing x such that $f(U) \subseteq V$.
3. $f([A]_{\delta - \mathcal{C}}) \subseteq [f(A)]_{\delta - \mathcal{C}}$, for each $A \subseteq X$.
4. $[f^{-1}(B)]_{\delta - \mathcal{C}} \subseteq f^{-1}([B]_{\delta - \mathcal{C}})$, for every $B \subseteq Y$.
5. For every $\delta - \mathcal{C}$ closed set F of Y , $f^{-1}(F)$ is $\delta - \mathcal{C}$ closed set in X .
6. For every $\delta - \mathcal{C}$ open set V of Y , $f^{-1}(V)$ is $\delta - \mathcal{C}$ open set in X .
7. For every $R - \mathcal{C}$ open set V of Y , $f^{-1}(V)$ is $\delta - \mathcal{C}$ open set in X .
8. For every $R - \mathcal{C}$ closed set F of Y , $f^{-1}(F)$ is $\delta - \mathcal{C}$ closed set in X .

Corollary 2.17 : [8] Let (X, τ, \mathcal{C}_1) and $(Y, \sigma, \mathcal{C}_2)$ be two convex topological spaces where (X, τ, \mathcal{C}_1) is $\tau - \mathcal{C}_1$ semi compatible and $(Y, \sigma, \mathcal{C}_2)$ is $\sigma - \mathcal{C}_2$ semi compatible. A function $f : (X, \tau, \mathcal{C}_1) \rightarrow (Y, \sigma, \mathcal{C}_2)$ is $\delta - \mathcal{C}$ continuous iff $f : (X, \tau_{\delta - \mathcal{C}_1}) \rightarrow (Y, \sigma_{\delta - \mathcal{C}_2})$ is continuous.

3. Comparison of different types of continuous functions :

Definition 3.1 : Let (X, τ, \mathcal{C}_1) and $(Y, \sigma, \mathcal{C}_2)$ be two convex topological spaces. A function $f : (X, \tau, \mathcal{C}_1) \rightarrow (Y, \sigma, \mathcal{C}_2)$ is said to be strongly $\theta - \mathcal{C}$ continuous [respectively $\theta - \mathcal{C}$ continuous, almost \mathcal{C} continuous] if for each $x \in X$ and each open nbd. V of $f(x)$, there exists an open nbd. U of x such that $f(U_*) \subseteq V$ [respectively $f(U_*) \subseteq V_*$, $f(U) \subseteq \text{int}(V_*)$].

Theorem 3.2 : (a) If a function $f : (X, \tau, \mathcal{C}_1) \rightarrow (Y, \sigma, \mathcal{C}_2)$ is strongly $\theta - \mathcal{C}$ continuous and $g : (Y, \sigma, \mathcal{C}_2) \rightarrow (Z, \gamma, \mathcal{C}_3)$ is almost \mathcal{C} continuous, then $g \circ f : (X, \tau, \mathcal{C}_1) \rightarrow (Z, \gamma, \mathcal{C}_3)$ is $\delta - \mathcal{C}$ continuous.

(b) The following implications hold :

strongly $\theta - \mathcal{C}$ continuous $\Rightarrow \delta - \mathcal{C}$ continuous \Rightarrow almost \mathcal{C} continuous .

Proof : (a) Let $x \in X$ and W be any open set containing $(g \circ f)(x)$. Since g is almost \mathcal{C} continuous , there exists an open nbd. V of $f(x)$ in Y such that $g(V) \subseteq \text{int}(W_*)$. Again since f is strongly $\theta - \mathcal{C}$ continuous , there exists an open nbd. U of x in X such that $f(U_*) \subseteq V$. So we get $g(f(U_*)) \subseteq g(V)$. Now $g(f(\text{int}(U_*))) \subseteq g(f(U_*)) \subseteq g(V) \subseteq \text{int}(W_*) \Rightarrow (g \circ f)(\text{int}(U_*)) \subseteq \text{int}(W_*)$. Hence $g \circ f$ is $\delta - \mathcal{C}$ continuous.

(b) Let f be strongly $\theta - \mathcal{C}$ continuous . Also let $x \in X$ and V be any open nbd. of $f(x)$. Then there exists an open nbd. U of x in X such that $f(U_*) \subseteq V$. Now $f(\text{int}(U_*)) \subseteq f(U_*) \subseteq V = \text{int}(V) \subseteq \text{int}(V_*)$. Hence f is $\delta - \mathcal{C}$ continuous .

Again let f be $\delta - \mathcal{C}$ continuous . Also let $x \in X$ and V be any open nbd. of $f(x)$ in Y . Then there exists an open nbd. U of x in X such that $f(\text{int}(U_*)) \subseteq \text{int}(V_*)$. Now $U = \text{int}(U) \subseteq \text{int}(U_*) \Rightarrow f(U) \subseteq f(\text{int}(U_*)) \subseteq \text{int}(V_*)$. Thus f is almost \mathcal{C} continuous .

Remark 3.3 : The following examples show that none of these implications in the above Theorem 3.2 is reversible .

Example 3.4 : Let $X = \{a, b, c\}$, $\tau = \{\phi, X, \{a\}\}$, $\mathcal{C}_1 = \{\phi, X\}$, $\sigma = \{\phi, X, \{b\}\}$, $\mathcal{C}_2 = \{\phi, X\}$ and the function $f : (X, \tau, \mathcal{C}_1) \rightarrow (X, \sigma, \mathcal{C}_2)$ be the identity function on X i.e., $f = I_X$. Here f is $\delta - \mathcal{C}$ continuous but not strongly $\theta - \mathcal{C}$ continuous .

Since for any $V \in \sigma$, we have $V_* = X$, we conclude that f is $\delta - \mathcal{C}$ continuous . Consider the point b in (X, τ, \mathcal{C}_1) . Now $\{b\}$ is an open nbd. of $b = f(b)$ in $(X, \sigma, \mathcal{C}_2)$. But there is no open nbd. U of b in (X, τ, \mathcal{C}_1) such that $f(U_*) \subseteq \{b\}$. Hence f is not strongly $\theta - \mathcal{C}$ continuous .

Example 3.5 : Let $X = \{a, b, c\}$, $\tau = \{\phi, X, \{a\}\}$, $\mathcal{C}_1 = \{\phi, X\}$, $\sigma = \{\phi, X, \{a\}, \{b\}, \{a, b\}\}$, $\mathcal{C}_2 = \{\phi, X, \{b\}\}$, and the function $f : (X, \tau, \mathcal{C}_1) \rightarrow (X, \sigma, \mathcal{C}_2)$ be the identity function on X . Here f is almost \mathcal{C} continuous but not $\delta - \mathcal{C}$ continuous function .

Clearly f is almost \mathcal{C} continuous function . Now consider the point a in (X, τ, \mathcal{C}_1) and $V = \{a\}$ be an open nbd. of $a = f(a)$ in $(X, \sigma, \mathcal{C}_2)$. In $(X, \sigma, \mathcal{C}_2)$, we have $\text{int}(V_*) = \text{int}(\{a\}_*) = \text{int}(\{a, c\}) = \{a\}$. Again in (X, τ, \mathcal{C}_1) open nbd. of $\{a\}$ are $\{a\}$ and X and $\text{int}(\{a\}_*) = \text{int}(X) = X$, $\text{int}(X_*) = X$. Thus there is no open nbd. of U of a in (X, τ, \mathcal{C}_1) such that $f(\text{int}(U_*)) \subseteq \text{int}(V_*)$. Hence f is not $\delta - \mathcal{C}$ continuous function .

Definition 3.6 : A convex topological space (X, τ, \mathcal{C}) is said to be an $SC - R$ space if for each $x \in X$ and each open nbd. V of x there exists an open nbd. U of x such that $x \in U \subseteq \text{int}(U_*) \subseteq V$.

Theorem 3.7 : For a function $f : (X, \tau, \mathcal{C}_1) \rightarrow (Y, \sigma, \mathcal{C}_2)$ the following properties are true :

(a) If Y is an $SC - R$ space and f is $\delta - \mathcal{C}$ continuous, then f is continuous .

(b) If X is an $SC - R$ space and f is almost \mathcal{C} continuous, then f is $\delta - \mathcal{C}$ continuous .

Proof : (a) Let Y be an $SC - R$ space and $x \in X$. Then for each open nbd. V of $f(x)$, there exists an open nbd. W of $f(x)$ such that $f(x) \in W \subseteq \text{int}(W_*) \subseteq V$. Since f is $\delta - \mathcal{C}$ continuous, there exists an open nbd. U of x such that $f(\text{int}(U_*)) \subseteq \text{int}(W_*)$. Since U is an open set, $f(U) = f(\text{int}(U)) \subseteq f(\text{int}(U_*)) \subseteq \text{int}(W_*) \subseteq V$ i.e., $f(U) \subseteq V$. Hence f is continuous .

(b) Let $x \in X$ and V be an open nbd. of $f(x)$. Since f is almost \mathcal{C} continuous, there exists an open nbd. U of x such that $f(U) \subseteq \text{int}(V_*)$. Again since X is an $SC - R$ space there exists an open nbd. W of x such that $\text{int}(W_*) \subseteq U$. Thus $f(\text{int}(W_*)) \subseteq f(U) \subseteq \text{int}(V_*)$. Hence f is $\delta - \mathcal{C}$ continuous .

Corollary 3.8 : If (X, τ, \mathcal{C}_1) and $(Y, \sigma, \mathcal{C}_2)$ are $SC - R$ spaces, then the concepts on a function $f : (X, \tau, \mathcal{C}_1) \rightarrow (Y, \sigma, \mathcal{C}_2)$, $\delta - \mathcal{C}$ continuity, continuity, almost \mathcal{C} continuity are equivalent .

Definition 3.9 : A function $f : (X, \tau, \mathcal{C}_1) \rightarrow (Y, \sigma, \mathcal{C}_2)$ is said to be almost $\mathcal{C} - open$ if for each $R - \mathcal{C}$ open set U in X , $f(U)$ is open in Y .

Theorem 3.10 : If a function $f : (X, \tau, \mathcal{C}_1) \rightarrow (Y, \sigma, \mathcal{C}_2)$ is $\theta - \mathcal{C}$ continuous and almost $\mathcal{C} - open$ where (X, τ, \mathcal{C}_1) is $\tau - \mathcal{C}_1$ semi compatible, then f is $\delta - \mathcal{C}$ continuous .

Proof : Let $x \in X$ and V be an open nbd. of $f(x)$. Since f is $\theta - \mathcal{C}$ continuous, there exists an open nbd. U of x such that $f(U_*) \subseteq V_*$. Thus $f(\text{int}(U_*)) \subseteq f(U_*) \subseteq V_*$. Now $\text{int}(U_*)$ is an $R - \mathcal{C}$ open set in X . Since f is almost $\mathcal{C} - open$, $f(\text{int}(U_*))$ is an open set in Y which is contained in V_* . So we have , $f(\text{int}(U_*)) \subseteq \text{int}(V_*)$. Hence f is a $\delta - \mathcal{C}$ continuous function .

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